

Uniform Derivation of Decision Procedures by
Superposition

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$$T \models L_1 \vee L_2 \vee \dots \vee L_k.$$

$$\Updownarrow$$

$$UnSat(T, \overline{L_1}, \dots, \overline{L_k})$$

$L_i = (s_i = t_i) \mid (s_i \neq t_i)$ – ground literals

T is **decidable** $\Leftrightarrow T \models C$ is decidable, C – ground clause

$\Leftrightarrow UnSat_T(S) := UnSat(T \cup S)$ is decidable,

S – set of ground literals

Decision algorithm for T is any algorithm that solves $UnSat_T(S)$.

Example 1

Theory of homomorphisms:^a
 $\mathcal{H} = \{h(f(x, y)) = f(h(x), h(y))\}$

Consider:

$$S := \{h(c) = c', h(c') = c, f(c, c') = h(h(a)), \\ f(c', c) = a, h(h(h(a))) \neq a\};$$

$$C := [h(c) = c', h(c') = c, f(c, c') = h(h(a)), \\ f(c', c) = a] \Rightarrow h(h(h(a))) = a;$$

(we abbreviate $L_1, \dots, L_k \Rightarrow L_{k+1}, \dots, L_s$ for
 $\overline{L_1} \vee, \dots, \overline{L_k} \vee L_{k+1} \vee \dots \vee L_s$)

Clearly $T \models C$, so S is \mathcal{H} -unsatisfiable.

^aActually, \mathcal{H} is decidable

Superposition calculus SP

Inference rules:

$$\textit{Superposition} \quad \frac{\Gamma \Rightarrow \Delta, l[u'] = r \quad \Pi \Rightarrow \Sigma, u = v}{\sigma(\Gamma, \Pi \Rightarrow \Delta, \Sigma, l[v] = r)}$$

$$\textit{Paramodulation} \quad \frac{\Gamma, l[u'] = r \Rightarrow \Delta \quad \Pi \Rightarrow \Sigma, u = v}{\sigma(l[v] = r, \Gamma, \Pi \Rightarrow \Delta, \Sigma)}$$

$$\textit{Reflection} \quad \frac{\Gamma, u' = u \Rightarrow \Delta}{\sigma(\Gamma \Rightarrow \Delta)}$$

$$\textit{Factoring} \quad \frac{\Gamma \Rightarrow \Delta, u = t, u' = t'}{\sigma(\Gamma, t = t' \Rightarrow \Delta, u = t')}$$

$\sigma = MGU(u, u')$, u' is not a variable in *Superposition* and *Paramodulation*.

Superposition calculus SP

Simplification rules:

$$\textit{Subsumption} \quad \frac{S \cup \{C, C'\}}{S \cup \{C\}} \quad \exists \theta(C) \subseteq C', \nexists \rho(C') = C$$

$$\textit{Simplification} \quad \frac{S \cup \{C[\theta(l)], l = r\}}{S \cup \{C[\theta(r)], l = r\}}$$

$$\textit{Deletion} \quad \frac{S \cup \{\Gamma \Rightarrow \Delta, t = t\}}{S}$$

Simplification rules have higher priority than inference rules.

Theorem 1.1 SP is *refutationally complete*:

$$\boxed{UnSat(T) \Rightarrow \forall T \vdash_{SP}^{fair} \{ \}}.$$

Theorem 1.1 gives us a **semi-decision** procedure for T :

$$\begin{array}{l} UnSat(T \cup S) \Rightarrow \mathcal{SP} \text{ derive empty clause} \\ \text{not } UnSat(T \cup S) \Rightarrow \mathcal{SP} \text{ may diverge} \end{array}$$

For some theories T \mathcal{SP} may give a **decision** procedure (Example: T - set of ground clauses).

We give an uniform \mathcal{SP} -based decision procedures for:

- Quantifier-free theory of equality
- Theory of Lists
- Theory of Arrays
- Theory of Arrays with Extensionality
- Theory of Lists and Arrays
- Theory of Homomorphisms

The scheme of the decision procedure based on
SP

1. “Flatten” the the input set of literals S ;
2. Show termination of SP on $\{\Gamma \cup S\}$ by specifying the clauses that may appear during derivation.

Flattening S

flat equality: $f(t_1, \dots, t_n) = t_0 \mid t_0 = f(t_1, \dots, t_n)$

distinction: $t_1 \neq t_2$

where t_i is either a variable or an individual constant;

Flat literals \Leftrightarrow flat equality of flat distinction;

Flat clause \Leftrightarrow disjunction of flat literals

Lemma 1.2 *Let T be a theory, S be a set of ground literals. Then there (eff.) exists S' – a finite set set of flat literals, such that*

$$UnSat_T\{S\} \Leftrightarrow UnSat_T S'$$

Example 2 The set from Example 2: $S = \{h(c) = c', h(c') = c,$

$f(c, c') = h(h(a))\}, f(c', c) = a, h(h(h(a))) \neq a\}$;

Can be flatten to $S' = \{h(c) = c', h(c') = c, f(c, c') = c_2,$

$f(c', c) = a, h(a) = c_1, h(c_1) = c_2, h(c_2) = c_3, c_3 \neq a\}$;

A Decision Procedure for the Quantifier-Free Theory of Equality

Theory \mathcal{E} :

<p style="text-align: center; color: blue;">Congruence axioms:</p> $x = x \quad (\text{R})$ $x = y \Rightarrow y = x \quad (\text{S})$ $x = y, y = z \Rightarrow x = z \quad (\text{T})$	<p style="text-align: center; color: blue;">substitutivity (Functional monotonicity):</p> $x = y \Rightarrow$ $f(\dots x \dots) = f(\dots y \dots)$
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Restriction on ordering \succ : $f(t_1, \dots, t_n) \succ c$ for every constant c .

Lemma 2.1 *Let S be a finite set of flat literals. Then $\mathcal{SP}\{S\}$ is finite.*

Proof. Saturation in \mathcal{SP} can produce only flat literals^a ■

^aSuperposition can never apply to ground flat literals since simplification has higher priority

A Decision Procedure for the Theory of Lists

$$Ax(\mathcal{L}) : \quad car(cons(x, y)) = x \quad (1)$$

$$cdr(cons(x, y)) = y \quad (2)$$

$$\mathcal{L} \Leftrightarrow \mathcal{E} + Ax(\mathcal{L})$$

Lemma 3.1 *Let S be a finite set of flat literals. Then the clauses occurring in $\mathcal{SP}\{L \cup S\}$ can be:*

- empty clauses
- ground flat literals
- $Ax(\mathcal{L})$

Proof. By case analysis of rules and assumptions. ■

Corollary 3.2 *For every set S of flat literals $\mathcal{SP}\{\mathcal{L} \cup S\}$ is finite. (In fact, $|\mathcal{SP}\{\mathcal{L} \cup S\}|$ is polynomial in $|S|$).*

Theorem 3.3 *\mathcal{SP} is a decision procedure for \mathcal{L} .*

A Decision procedure for the Theory of Arrays

$$Ax(\mathcal{A}) : \quad select(store(a, i, e), i) = e \quad (3)$$

$$i \neq j \Rightarrow select(store(a, i, e), j) = select(a, j) \quad (4)$$

$\mathcal{A} \Leftrightarrow \mathcal{E} + Ax(\mathcal{A})$ Restriction: $t \succ s$ if

- 1) t contains *select* or *store*, but s is not and closed.
- 2) t is non-constant, s is constant.

Lemma 4.1 *Let S be a finite set of flat literals. The clauses occurring in the saturations of $S \cup Ax(\mathcal{A})$ by \mathcal{SP} can only be:*

- *the empty clauses;*
- *the axioms in $Ax(\mathcal{A})$;*
- *ground flat literals*
- *$t \bowtie t' \vee c_1 = c'_1 \vee \dots \vee c_n = c'_n$, where*
 $t \bowtie t' \in \{c' \neq c''\} \cup \{t = t' \mid t, t' \in \{c_i, select(c_i, i)\}\}$
- *$select(c, x) = select(c', x) \vee c_1 = k_1 \vee \dots \vee c_n = k_n$, where*
 $k_i \in \{x, c, c', c_1, c'_1, \dots, c_n, c'_n\}$

A Decision procedure for the Theory of Arrays

Lemma 4.1 *Let S be a finite set of flat literals. The clauses occurring in the saturations of $S \cup Ax(\mathcal{A})$ by \mathcal{SP} can only be:*

- *the empty clauses;*
- *the axioms in $Ax(\mathcal{A})$;*
- *ground flat literals*
- *$t \bowtie t' \vee c_1 = c'_1 \vee \dots \vee c_n = c'_n$, where
 $t \bowtie t' \in \{c' \neq c''\} \cup \{t = t' \mid t, t' \in \{c_i, \text{select}(c_i, i)\}\}$*
- *$\text{select}(c, x) = \text{select}(c', x) \vee c_1 = k_1 \vee \dots \vee c_n = k_n$, where
 $k_i \in \{x, c, c', c_1, c'_1, \dots, c_n, c'_n\}$*

Corollary 4.2 *For S being a finite set of flat literals. Then every saturation by \mathcal{SP} of $\{\mathcal{A} \cup S\}$ is finite.*

Theorem 4.3 *\mathcal{SP} is a decision procedure for \mathcal{A} .*

A Decision procedure for the Theory of Arrays with Extensionality

\mathcal{A}^s is a many sorted version of \mathcal{A} .

$$\mathcal{A}_e^s \Leftrightarrow \mathcal{A}^s + \boxed{\forall i. (select(a, i) = select(b, i)) \Rightarrow a = b} \quad (5)$$

Additional assumptions:

- $f \neq select, store, f : s_0, \dots, s_{n-1} \rightarrow s_n$ then $s_i \neq ARRAY$;
- $\Sigma_{\mathcal{A}_e^s}$ is sensible (there is at least one ground term for each sort).

Given S being a set of ground literals we proceed by:

1. “**Lifting of inequalities**”: $t \neq t' \rightarrow \exists i. select(t, i) \neq select(t', i)$;

Lemma 5.1 S is \mathcal{A}_e^s -satisfiable iff S' is \mathcal{A}^s -satisfiable.

2. “**Skolemization**”: $\exists i. select(t, i) \neq select(t', i) \rightarrow select(t, sk(t, t')) \neq select(t', sk(t, t'))$

Theorem 5.2 S' is \mathcal{A}^s -satisfiable iff S'' is \mathcal{A} -satisfiable.

3. Apply the decision procedure for \mathcal{A} .

Combining Decision Procedures for Lists and Arrays

$$Ax(\mathcal{U}) = Ax(\mathcal{L}) + Ax(\mathcal{A}); \mathcal{U} = Ax(\mathcal{U}) + \mathcal{E}$$

Lemma 6.1 *Let S be a finite set of ground flat literals. The clauses in $\mathcal{SP}\{S \cup Ax(\mathcal{U})\}$ can only be of the types, specifying in Lemma 3.1 and Lemma 4.1.*

Lemma 6.2 *All the saturations of $S \cup Ax(\mathcal{U})$ by \mathcal{SP} are finite.*

Theorem 6.3 *\mathcal{SP} is a decision procedure for \mathcal{U} .*

A Decision Procedure for the Theory of Homomorphism

Recall: $Ax(\mathcal{H}) \Leftarrow \boxed{h(f(x_1, \dots, x_n)) = f(h(x_1), \dots, h(x_n))} \quad (6)$

$\mathcal{H} = Ax(\mathcal{H}) + \mathcal{E}$

Sketch of the Decision procedure^a

Given a set Ψ of ground literals we:

1. Flatten Ψ
- 2. Complete the set of (ground) equalities in Ψ modulo $Ax(\mathcal{H})$ in order to get a rewrite system \mathcal{R} .
3. For each inequality $s \neq t$ in Ψ compute the normal forms $s' = s \downarrow_{\mathcal{R}}$, $t' = t \downarrow_{\mathcal{R}}$ w.r.t. \mathcal{R} . If there exists $s \neq t \in \Psi$ s.t. $s' = t'$ then Ψ is \mathcal{H} -unsatisfiable; otherwise Ψ is \mathcal{H} -satisfiable.

^aactually it's an adaptation of the Knuth-Bendix completion procedure:

Completion

Orientation:

We want \mathcal{SP} to generate only **ground** literals. For this reason we should orient $Ax(\mathcal{H})$ by the following way:

$$h(f(x_1, \dots, x_n)) \succ f(h(x_1), \dots, h(x_n))$$

otherwise, *superposition* between

$$f(h(x_1), \dots, h(x_n)) = h(f(x_1, \dots, x_n)) \text{ and } h(c_1) = c$$

will give us $f(c, h(x_2), \dots, h(x_n)) = h(f(c_1, x_2, \dots, x_n))$.

Problem: $\mathcal{SP}\{h(c) = c, f(c, c') = c, Ax(\mathcal{H})\}$ generates

$$f(c, h^n(c')) = c \quad \forall n \geq 0.$$

\Rightarrow We **cannot** argue that $\mathcal{SP}\{S \cup \mathcal{H}\}$ is finite.

However, decision procedure for \mathcal{H} can be constructed by using a special **rule of inference** additional to \mathcal{SP} instead of $Ax(\mathcal{H})$ using so-called **completion procedure**.

Discussion

- ? what kind of **uniformness** in applying \mathcal{SP} as a decision procedure?
- ? is there a **decidable** theories to which \mathcal{SP} cannot be applied as a decision procedure? [Yes].
- ? how to check whether \mathcal{SP} can be applied to a theory as a decision procedure?
- ? is there a **universal** decision procedure that can be applied to any **decidable** theory? [Skeptical]
- ? what is the time complexity of these decision procedures w.r.t. the best time complexities?
- ? what is the relationship between congruence closure and \mathcal{SP} (applicability, complexity)?