



Algorithms and Data Structures K. Mehlhorn and R. Seidel Final Exam

1. (10 points) Let G = (V, E) be an undirected graph, and assume that some of the edges in *E* are designated as "bad."

How can you find a spanning tree of G that contains as few bad edges as possible?

How fast can you construct such a spanning tree?

2. (20 points) In this question we consider hash functions from a key universe $U = \{0, ..., t - 1\}^d$ to table indices $\{0, ..., t - 1\}$. Here *d* is some fixed integer greater than 1 and *t* is a prime number.

For each *d*-tuple $a = \langle a_1, \ldots, a_d \rangle \in U$ define the function

$$h_a(x) = \sum_{1 \le i \le d} a_i x_i \bmod t \,,$$

where $x = \langle x_1, \ldots, x_d \rangle \in U$.

In class we showed that the set

$$\mathscr{H}_0 = \{h_a; a \in U\}$$

forms a universal set of hash functions.

The random choice of a function from \mathcal{H}_0 requires to choose *d* random numbers a_1, \ldots, a_d from $\{0, \ldots, t-1\}$.

(a) Would it also suffice to choose just d-1 random numbers? In other words, is the set

$$\mathscr{H}_1 = \left\{ h_a \, | \, a = \langle 1, a_2, \dots, a_d \rangle \in \{0, \dots, t-1\}^d \right\}$$

universal?

(b) Would it also suffice to choose just d-2 random numbers? In other words, is the set

$$\mathscr{H}_2 = \left\{ h_a \, | \, a = \langle 1, 1, a_3, \dots, a_d \rangle \in \{0, \dots, t-1\}^d \right\}$$

universal?

3. (15 points) We are given a set S of n nonintersecting line segments and a set P of n points. We want to find all pairs $(p,s) \in P \times S$ such that p lies on s. Design an algorithm and analyze its running time.

Summer 2008 Tue, Oct. 7th 14:30 – 16:30 4. (20 points) Let S be a set of n disjoint line segments in the plane, and let p be a point that does not lie on any of the segments in S. We wish to determine all segments in S that p can see, i.e., all segments s that contain some point q so that the open line segments \overline{pq} does not intersect any segment of S. Describe an $O(n \log n)$ algorithm that uses a rotating half-line with its endpoint at p. In the figure below, the segments t_1 and t_2 are not visible from p; all other segments are visible.



5. (15 points) Is the following statement true or false? If true, give a short explanation, if false, give a counterexample.

Let G = (V, E) be a directed graph, $s \in V$ a source vertex, $t \in V$ a sink vertex, and $cap : E \rightarrow$ IN a capacity function. Let (S, T) be a minimum *s*-*t* cut. Now suppose that we increase all capacities by one; then (S, T) is also a minimum *s*-*t* cut for the modified capacities.

- 6. (20 points) Let G = (V, E) be a directed graph, $cap : E \to \mathbb{N}$ a capacity function, $c : E \to \mathbb{N}$ a cost function, and $b : V \to \mathbb{Z}$ a demand/supply function with $\sum_{v} b(v) = 0$.
 - (a) Let $f : E \to \mathbb{N}$ be a flow. Describe how to check whether f is a minimum cost flow satisfying the demands and supplies. What is the running time of your method?
 - (b) Argue that there is a minimum cost flow in which the flow across each edge is integral. Observe that all capacities and costs are integral.
 - (c) Assume that f is a minimum cost flow. We increase the cost of one edge by one. Describe how to update f so that it becomes a minimum cost flow for the modified network. What is the cost of updating f?
- 7. (30 points) Let G = (V,E) be a directed graph and let s ∈ V be a designated node. For a subset F ⊆ E of the edges, let q(F) be the number of nodes that are not reachable from s in (V,E \ F). We want to find the F that maximizes g(F) := q(F) |F|; for F = Ø, we have g(F) = 0. Describe a polynomial time algorithm for finding such an F.

Cake and coffee are served at 16:45 on first floor of MPI building.