



Translating Hausdorff Is Hard: Fine-Grained Lower Bounds for Hausdorff Distance Under Translation

Karl Bringmann and **André Nusser**

Eine Menge ist eine Zusammenfassung von Dingen zu einem Ganzen, d.h., zu einem neuen Ding. Man wird dies allerdings schwerlich ...



translation

A set is a ???? of ??? ?? ? ? ?
?? ???? ?????? ?????? ?????
?????, i.e., ??? ? ?????. ?????
??...



Preamble

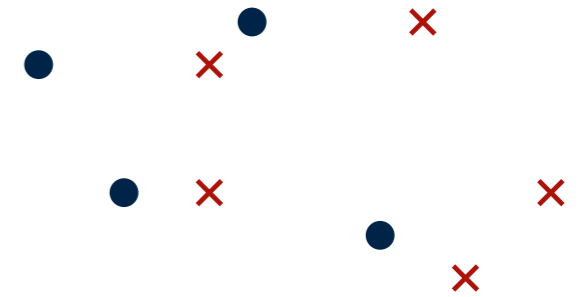


Hausdorff Distance

Given: Point sets A (●) and B (×) in \mathbb{R}^2

Directed Hausdorff Distance

$$\delta_{\vec{H}}(A, B) := \max_{a \in A} \min_{b \in B} \|a - b\|_p$$

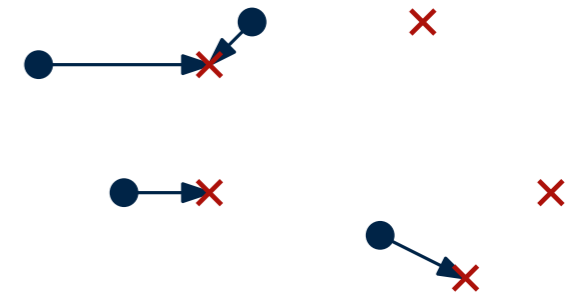


Hausdorff Distance

Given: Point sets A (●) and B (×) in \mathbb{R}^2

Directed Hausdorff Distance

$$\delta_{\vec{H}}(A, B) := \max_{a \in A} \min_{b \in B} \|a - b\|_p$$

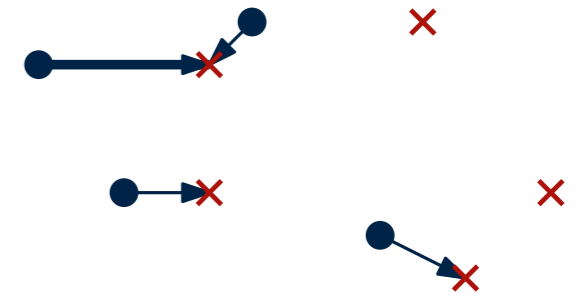


Hausdorff Distance

Given: Point sets A (●) and B (×) in \mathbb{R}^2

Directed Hausdorff Distance

$$\delta_{\vec{H}}(A, B) := \max_{a \in A} \min_{b \in B} \|a - b\|_p$$



Hausdorff Distance

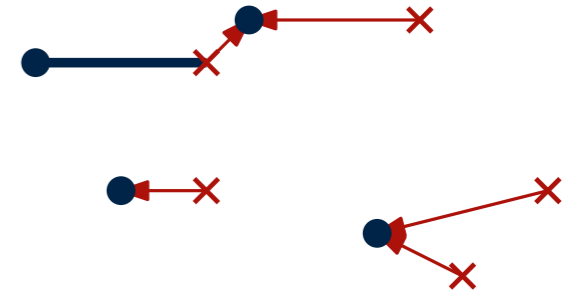
Given: Point sets A (●) and B (×) in \mathbb{R}^2

Directed Hausdorff Distance

$$\delta_{\vec{H}}(A, B) := \max_{a \in A} \min_{b \in B} \|a - b\|_p$$

(Undirected) Hausdorff Distance

$$\delta_H(A, B) := \max\{\delta_{\vec{H}}(A, B), \delta_{\vec{H}}(B, A)\}$$



Hausdorff Distance

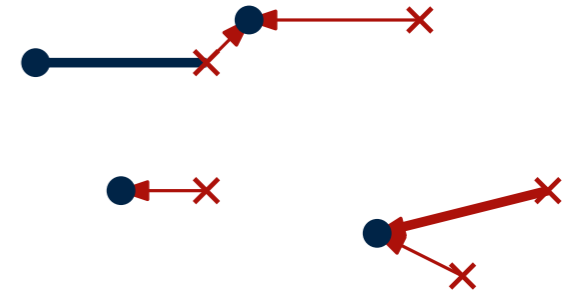
Given: Point sets A (●) and B (×) in \mathbb{R}^2

Directed Hausdorff Distance

$$\delta_{\vec{H}}(A, B) := \max_{a \in A} \min_{b \in B} \|a - b\|_p$$

(Undirected) Hausdorff Distance

$$\delta_H(A, B) := \max\{\delta_{\vec{H}}(A, B), \delta_{\vec{H}}(B, A)\}$$



Hausdorff Distance

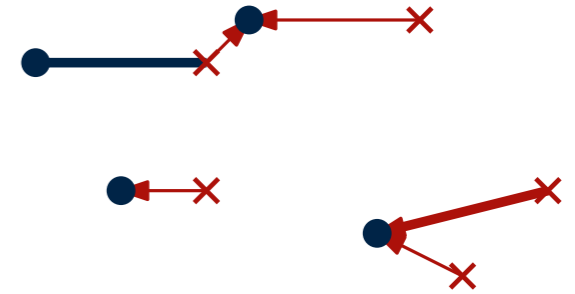
Given: Point sets A (●) and B (×) in \mathbb{R}^2

Directed Hausdorff Distance

$$\delta_{\vec{H}}(A, B) := \max_{a \in A} \min_{b \in B} \|a - b\|_p$$

(Undirected) Hausdorff Distance

$$\delta_H(A, B) := \max\{\delta_{\vec{H}}(A, B), \delta_{\vec{H}}(B, A)\}$$



→ Computable in time $\tilde{O}(n + m)$

Hausdorff Distance

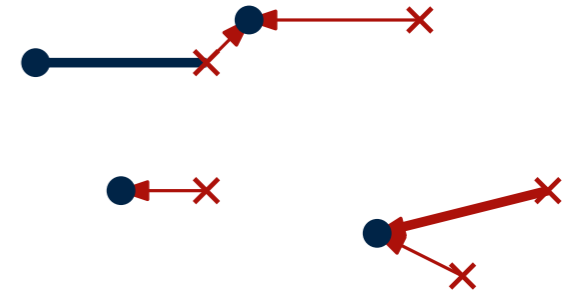
Given: Point sets A (●) and B (×) in \mathbb{R}^2

Directed Hausdorff Distance

$$\delta_{\vec{H}}(A, B) := \max_{a \in A} \min_{b \in B} \|a - b\|_p$$

(Undirected) Hausdorff Distance

$$\delta_H(A, B) := \max\{\delta_{\vec{H}}(A, B), \delta_{\vec{H}}(B, A)\}$$



→ Computable in time $\tilde{O}(n + m)$

Hausdorff Distance Under Translation

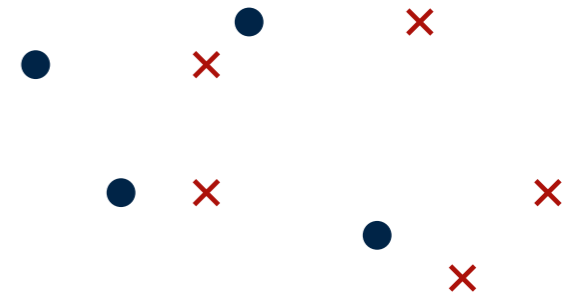
Given: Point sets A (●) and B (×) in \mathbb{R}^2

Directed Hausdorff Distance U. Translation

$$\delta_{\vec{H}}^T(A, B) := \min_{\tau \in \mathbb{R}^2} \delta_{\vec{H}}(A, B + \tau)$$

(Undirected) Hausdorff Distance U. Translation

$$\delta_H^T(A, B) := \min_{\tau \in \mathbb{R}^2} \delta_H(A, B + \tau)$$



Hausdorff Distance Under Translation

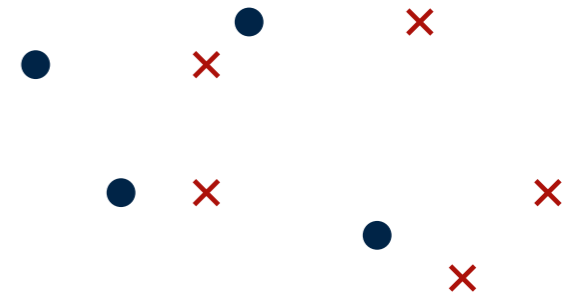
Given: Point sets A (●) and B (×) in \mathbb{R}^2

Directed Hausdorff Distance U. Translation

$$\delta_{\vec{H}}^T(A, B) := \min_{\tau \in \mathbb{R}^2} \delta_{\vec{H}}(A, B + \tau)$$

(Undirected) Hausdorff Distance U. Translation

$$\delta_H^T(A, B) := \min_{\tau \in \mathbb{R}^2} \delta_H(A, B + \tau)$$



Hausdorff Distance Under Translation

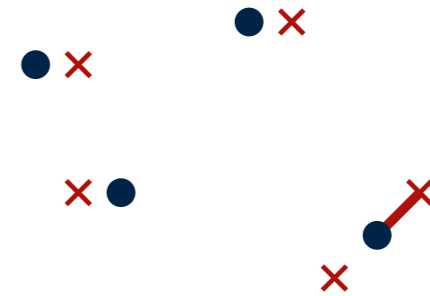
Given: Point sets A (●) and B (×) in \mathbb{R}^2

Directed Hausdorff Distance U. Translation

$$\delta_{\vec{H}}^T(A, B) := \min_{\tau \in \mathbb{R}^2} \delta_{\vec{H}}(A, B + \tau)$$

(Undirected) Hausdorff Distance U. Translation

$$\delta_H^T(A, B) := \min_{\tau \in \mathbb{R}^2} \delta_H(A, B + \tau)$$



Hausdorff Distance Under Translation

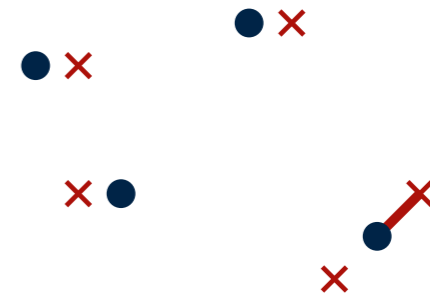
Given: Point sets A (●) and B (×) in \mathbb{R}^2

Directed Hausdorff Distance U. Translation

$$\delta_{\vec{H}}^T(A, B) := \min_{\tau \in \mathbb{R}^2} \delta_{\vec{H}}(A, B + \tau)$$

(Undirected) Hausdorff Distance U. Translation

$$\delta_H^T(A, B) := \min_{\tau \in \mathbb{R}^2} \delta_H(A, B + \tau)$$



→ What's the “correct” running time?

Motivation

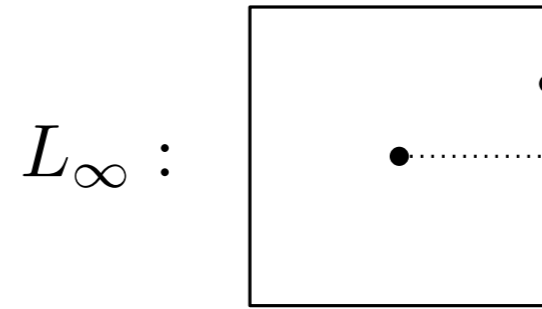
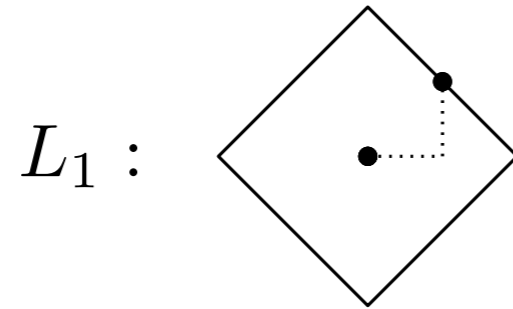
Most basic translation invariant point set similarity measure



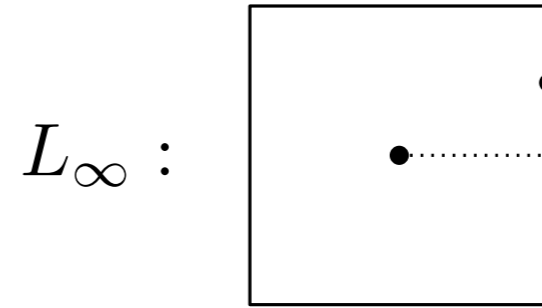
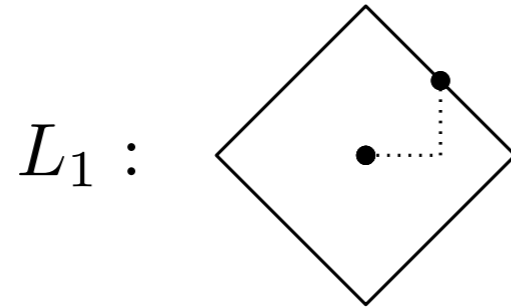
Results



Results



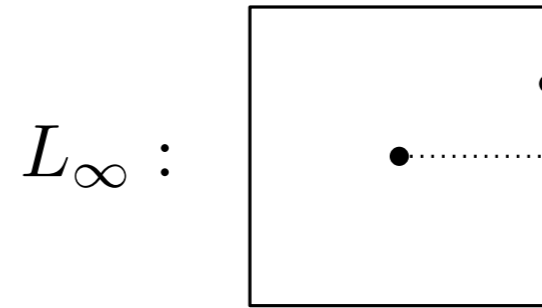
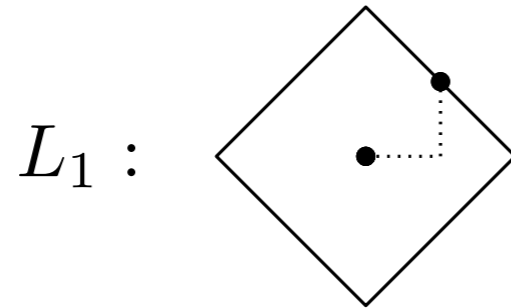
Results



Theorem [Chew, Kedem '92]

Hausdorff Distance Under Translation in L_1/L_∞ can be computed in time $\tilde{O}(nm)$.

Results



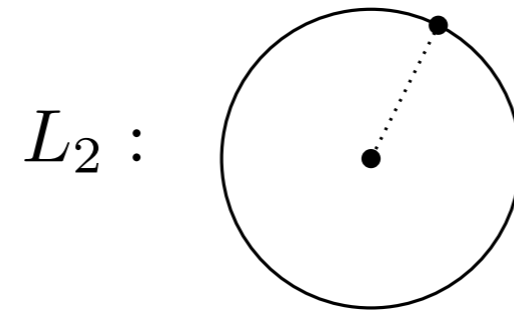
Theorem [Chew, Kedem '92]

Hausdorff Distance Under Translation in L_1/L_∞ can be computed in time $\tilde{O}(nm)$.

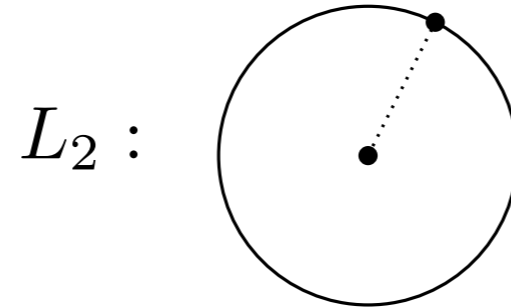
Theorem

Hausdorff Distance Under Translation in L_1/L_∞ cannot be computed in time $(nm)^{1-\epsilon}$, unless SETH fails.

Results



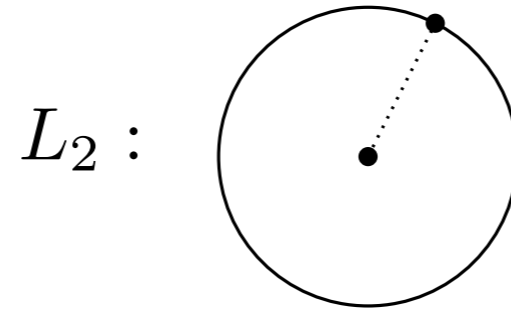
Results



Theorem [Huttenlocher, Kedem, Sharir '93]

Hausdorff Distance Under Translation in L_2 can be computed in $\tilde{O}(nm(n+m))$.

Results



Theorem [Huttenlocher, Kedem, Sharir '93]

Hausdorff Distance Under Translation in L_2 can be computed in $\tilde{O}(nm(n+m))$.

Theorem

Hausdorff Distance Under Translation in L_2 with $m \in \mathcal{O}(1)$ cannot be computed in time $n^{2-\epsilon}$, unless the 3SUM Hypothesis fails.

First Reduction



Theorem

Hausdorff Distance Under Translation in L_1/L_∞ cannot be computed in time $(nm)^{1-\epsilon}$, unless SETH fails.

Orthogonal Vectors

Orthogonal Vectors (OV)

Given sets $X, Y \subset \{0, 1\}^d$, do there exist $x \in X$ and $y \in Y$ such that $\langle x, y \rangle = 0$?

Orthogonal Vectors

Orthogonal Vectors (OV)

Given sets $X, Y \subset \{0, 1\}^d$, do there exist $x \in X$ and $y \in Y$ such that $\langle x, y \rangle = 0$?

Orthogonal Vectors Hypothesis (OVH)

Orthogonal Vectors cannot be solved in time $\mathcal{O}((|X| \cdot |Y|)^{1-\epsilon} \text{poly}(d))$.

Orthogonal Vectors

Orthogonal Vectors (OV)

Given sets $X, Y \subset \{0, 1\}^d$, do there exist $x \in X$ and $y \in Y$ such that $\langle x, y \rangle = 0$?

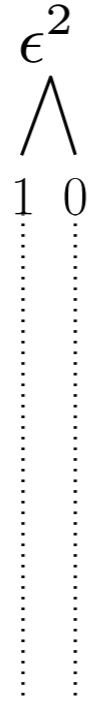
Orthogonal Vectors Hypothesis (OVH)

Orthogonal Vectors cannot be solved in time $\mathcal{O}((|X| \cdot |Y|)^{1-\epsilon} \text{poly}(d))$.

→ SETH implies OVH [Williams '05]

$$OV \leq \delta_H^T \text{ in } L_1$$

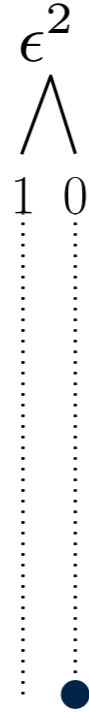
Vector Gadgets



$$x = (0, 1, 1, 0, 1, 0, 0)$$

$$OV \leq \delta_H^T \text{ in } L_1$$

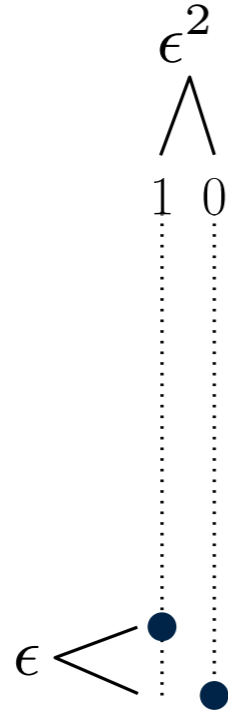
Vector Gadgets



$$x = (0, 1, 1, 0, 1, 0, 0)$$

$$OV \leq \delta_H^T \text{ in } L_1$$

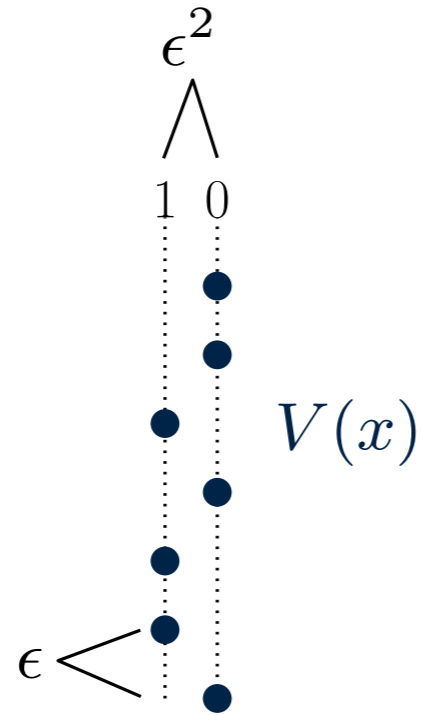
Vector Gadgets



$$x = (0, 1, 1, 0, 1, 0, 0)$$

$$OV \leq \delta_H^T \text{ in } L_1$$

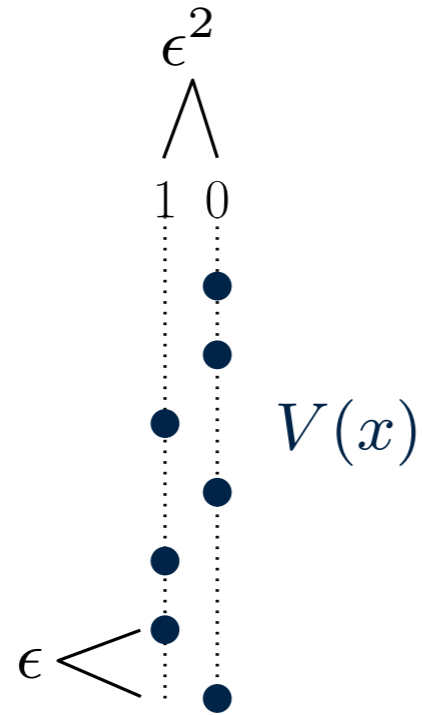
Vector Gadgets



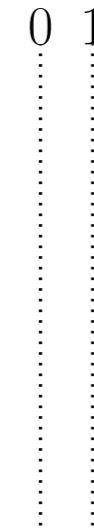
$$x = (0, 1, 1, 0, 1, 0, 0)$$

$$OV \leq \delta_H^T \text{ in } L_1$$

Vector Gadgets



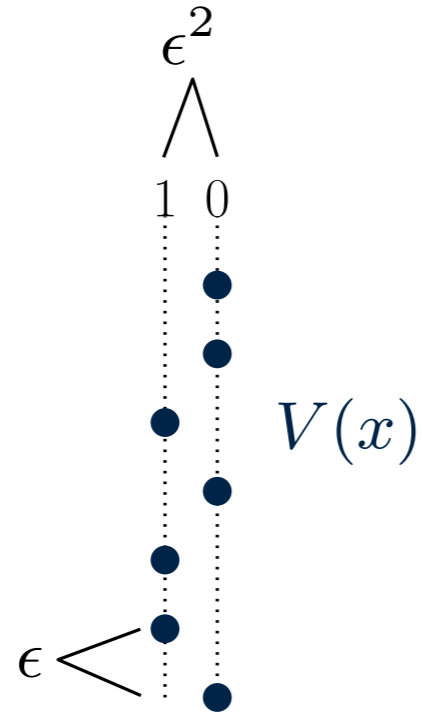
$$x = (0, 1, 1, 0, 1, 0, 0)$$



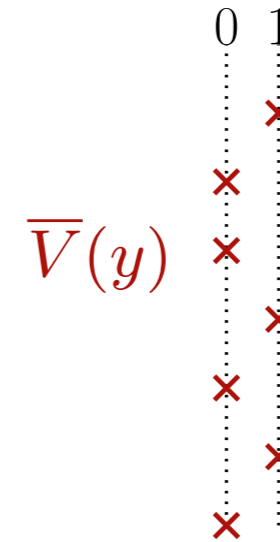
$$y = (0, 1, 0, 1, 0, 0, 1)$$

$$OV \leq \delta_H^T \text{ in } L_1$$

Vector Gadgets



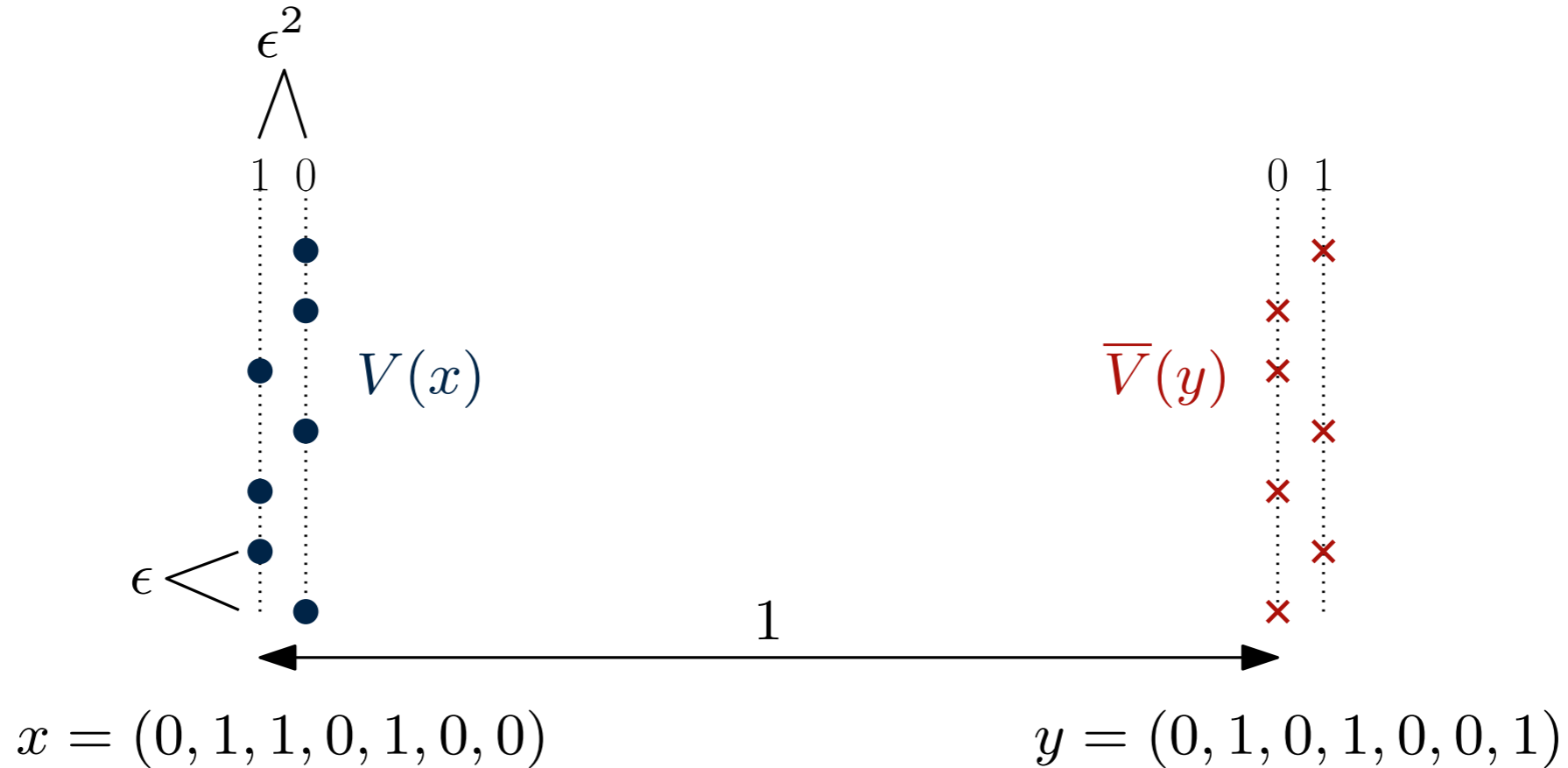
$$x = (0, 1, 1, 0, 1, 0, 0)$$



$$y = (0, 1, 0, 1, 0, 0, 1)$$

$$OV \leq \delta_H^T \text{ in } L_1$$

Vector Gadgets



Hausdorff distance at most 1 $\iff \langle x, y \rangle = 0$

$$OV \leq \delta_H^T \text{ in } L_1$$

Choice Gadget

OV Input:

$$X = \{x_1, \dots, x_4\}$$

$$Y = \{y_1, \dots, y_3\}$$



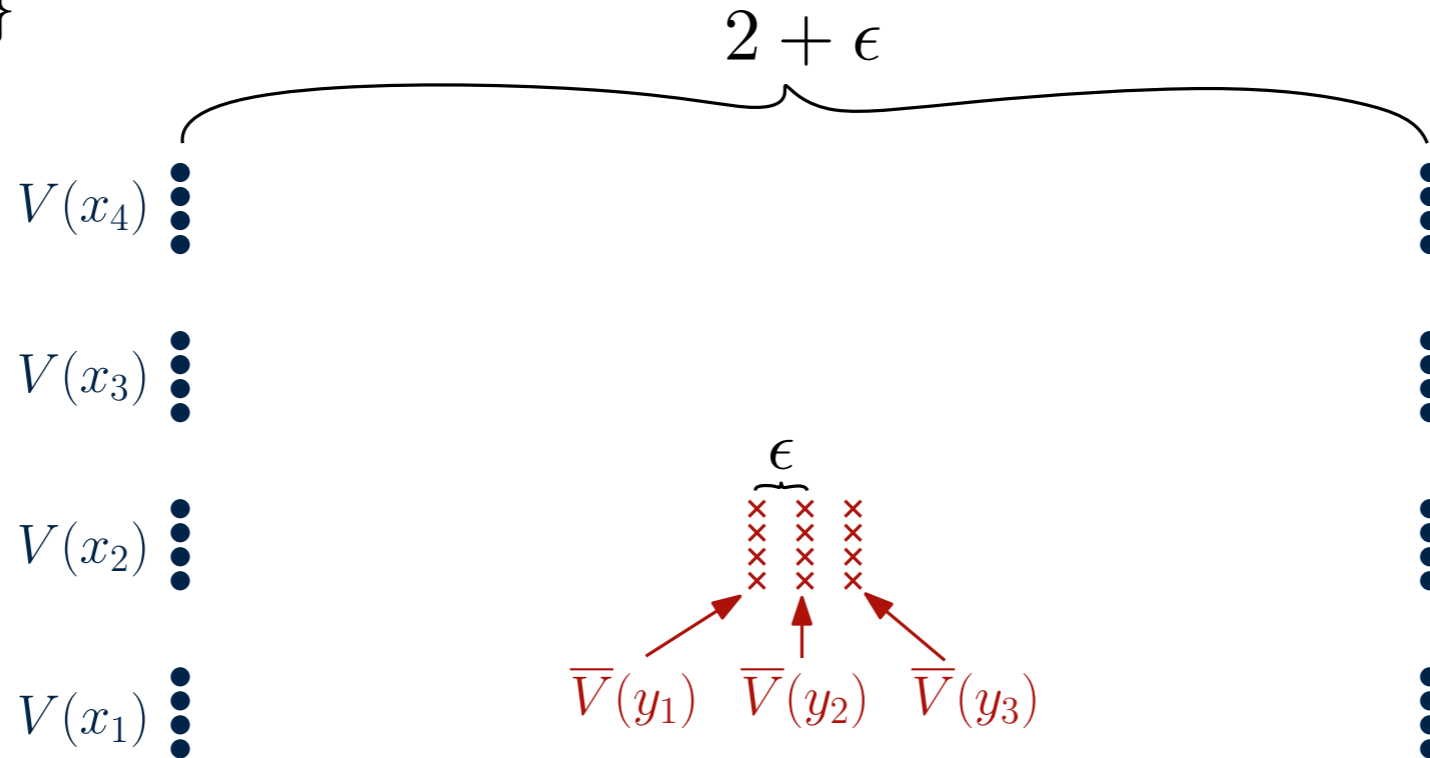
$$OV \leq \delta_H^T \text{ in } L_1$$

Choice Gadget

OV Input:

$$X = \{x_1, \dots, x_4\}$$

$$Y = \{y_1, \dots, y_3\}$$



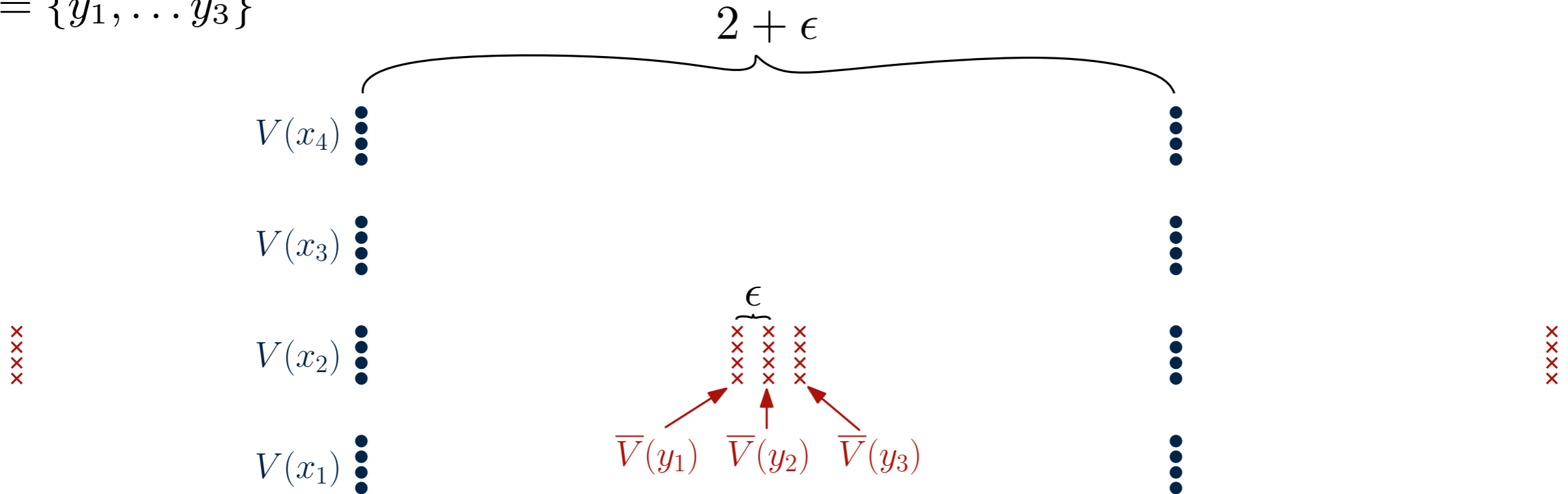
$$OV \leq \delta_H^T \text{ in } L_1$$

Choice Gadget

OV Input:

$$X = \{x_1, \dots, x_4\}$$

$$Y = \{y_1, \dots, y_3\}$$



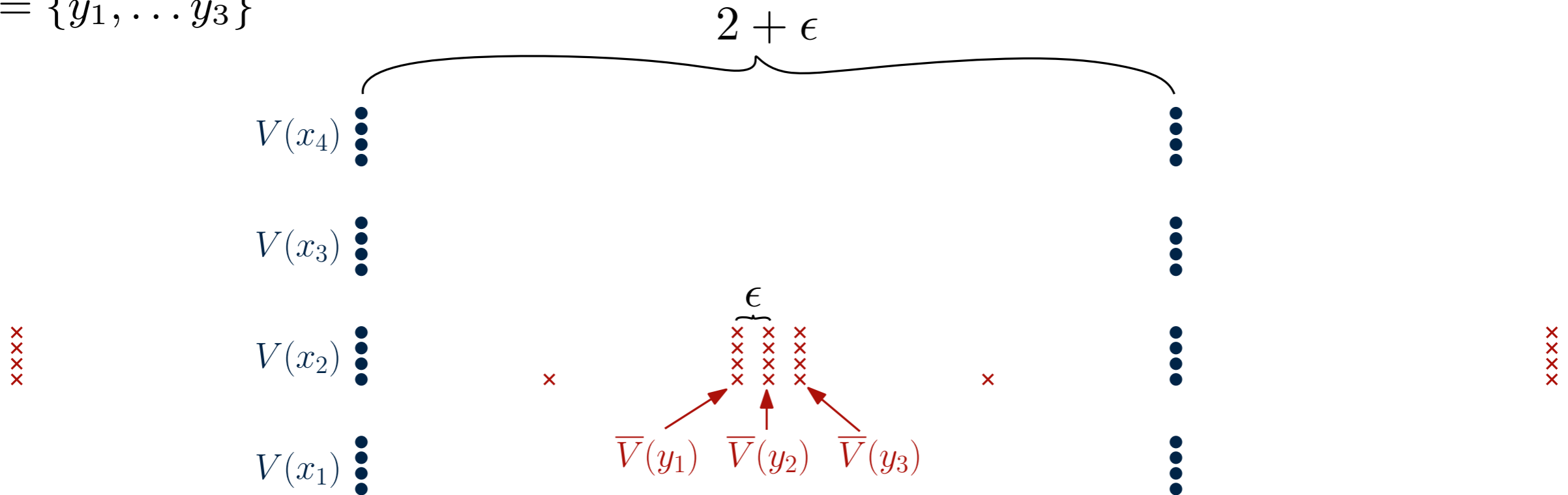
$$OV \leq \delta_H^T \text{ in } L_1$$

Choice Gadget

OV Input:

$$X = \{x_1, \dots, x_4\}$$

$$Y = \{y_1, \dots, y_3\}$$



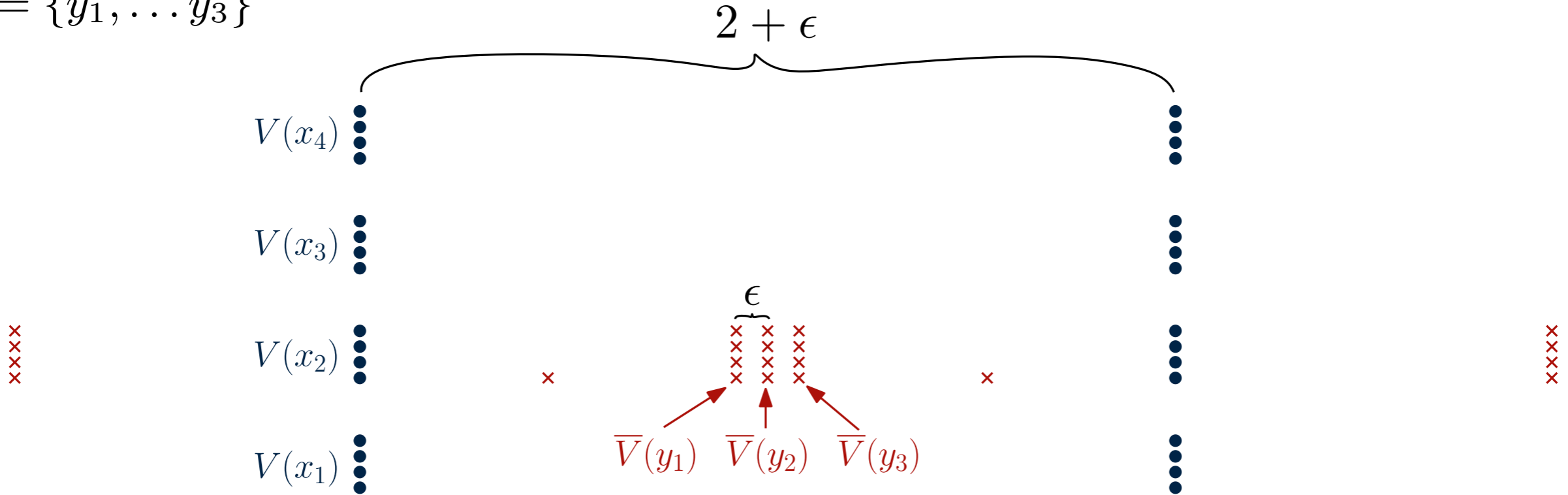
$$OV \leq \delta_H^T \text{ in } L_1$$

Choice Gadget

OV Input:

$$X = \{x_1, \dots, x_4\}$$

$$Y = \{y_1, \dots, y_3\}$$



Hausdorff distance under translation at most 1 $\iff \exists i, j : \langle x_i, y_j \rangle = 0$

Second Reduction



Theorem

Hausdorff Distance Under Translation in L_2 with $m \in \mathcal{O}(1)$ cannot be computed in time $n^{2-\epsilon}$, unless the 3SUM Hypothesis fails.



3SUM

3SUM Problem

Given $X = (x_0, \dots, x_{n-1}) \subset \{1, \dots, \text{poly}(n)\}$, do there exist $i, j, k \in [n]$ s.t.

$$x_i + x_j = x_k$$

3SUM

3SUM Problem

Given $X = (x_0, \dots, x_{n-1}) \subset \{1, \dots, \text{poly}(n)\}$, do there exist $i, j, k \in [n]$ s.t.

$$x_i + x_j = x_k$$

3SUM Hypothesis

The 3SUM Problem cannot be solved in time $n^{2-\epsilon}$.

3SUM

Convolution

3SUM Problem

Given $X = (x_0, \dots, x_{n-1}) \subset \{1, \dots, \text{poly}(n)\}$, do there exist $i, j, \cancel{k} \in [n]$ s.t.

$$x_i + x_j = x_{\cancel{k}}$$

$i+j$

3SUM Hypothesis

The 3SUM Problem cannot be solved in time $n^{2-\epsilon}$.

3SUM

Convolution

3SUM Problem

Given $X = (x_0, \dots, x_{n-1}) \subset \{1, \dots, \text{poly}(n)\}$, do there exist $i, j, \cancel{k} \in [n]$ s.t.

$$x_i + x_j = x_{\cancel{k}}$$

$i+j$

Convolution

3SUM Hypothesis

Convolution

The \checkmark 3SUM Problem cannot be solved in time $n^{2-\epsilon}$.

3SUM

Convolution

3SUM Problem

Given $X = (x_0, \dots, x_{n-1}) \subset \{1, \dots, \text{poly}(n)\}$, do there exist $i, j, \cancel{k} \in [n]$ s.t.

$$x_i + x_j = x_{\cancel{k}}$$

$i+j$

Convolution

3SUM Hypothesis

Convolution

The 3SUM Problem cannot be solved in time $n^{2-\epsilon}$.

→ 3SUM and Convolution 3SUM Hypotheses are equivalent [Pătraşcu '10]



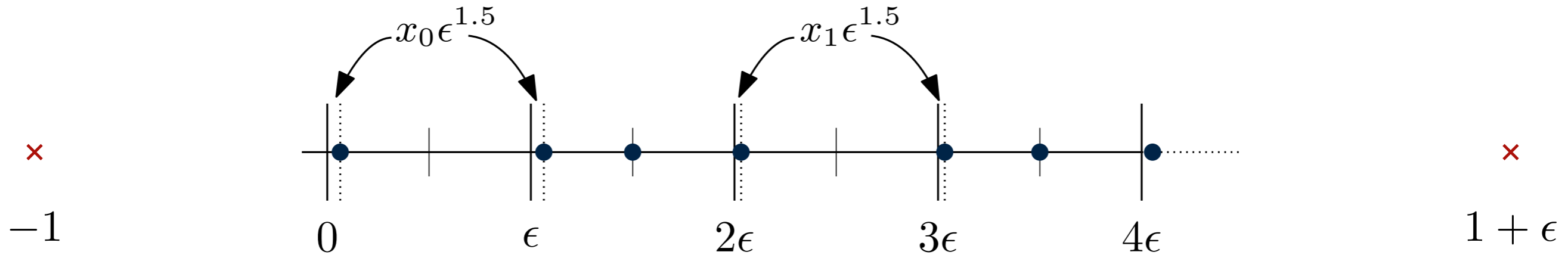
$$\text{Conv3SUM} \leq \delta_H^T \text{ in } L_2$$

Encode the sequence $X = (x_0, \dots, x_{n-1})$:



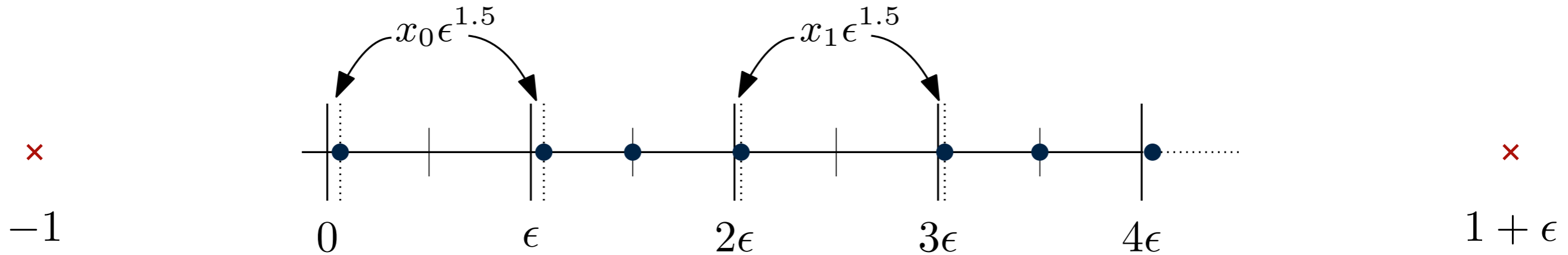
$$\text{Conv3SUM} \leq \delta_H^T \text{ in } L_2$$

Encode the sequence $X = (x_0, \dots, x_{n-1})$:



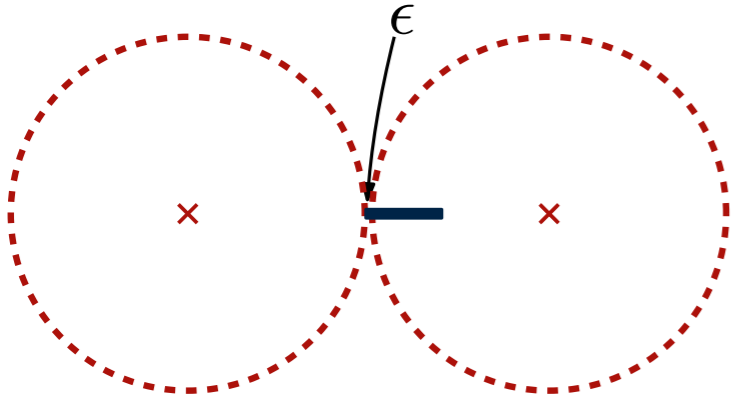
$$\text{Conv3SUM} \leq \delta_H^T \text{ in } L_2$$

Encode the sequence $X = (x_0, \dots, x_{n-1})$:



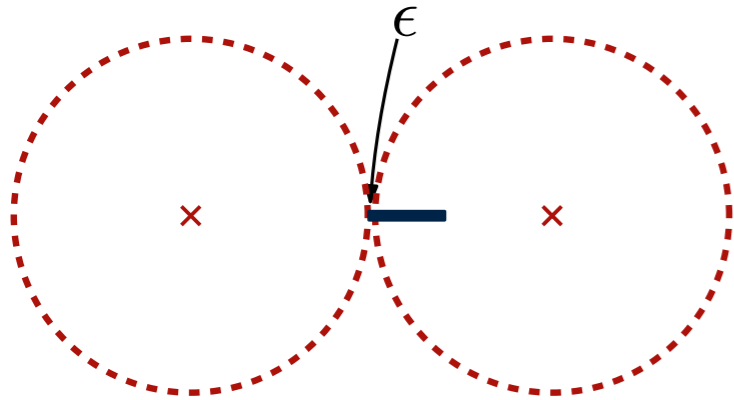
Feasible translations: $\tau_x \approx 2i\epsilon + x_i \epsilon^{1.5}$ for $i \in [n]$

$$\text{Conv3SUM} \leq \delta_H^T \text{ in } L_2$$

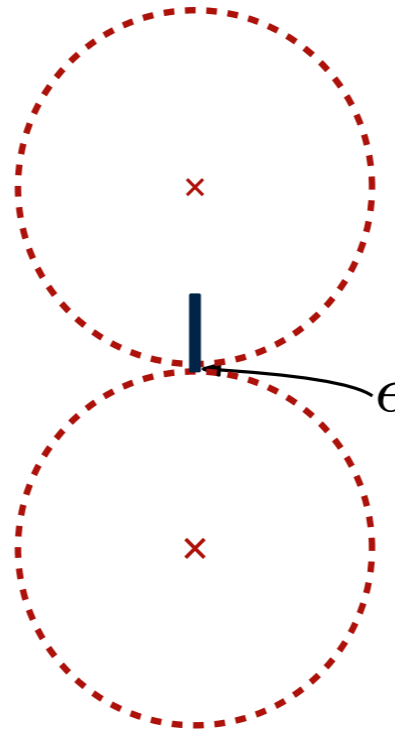


$$\tau_x \approx 2i\epsilon + x_i\epsilon^{1.5}$$

$$\text{Conv3SUM} \leq \delta_H^T \text{ in } L_2$$

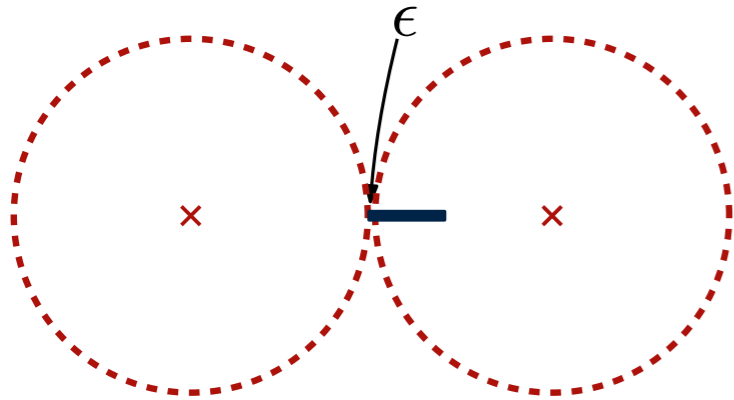


$$\tau_x \approx 2i\epsilon + x_i\epsilon^{1.5}$$

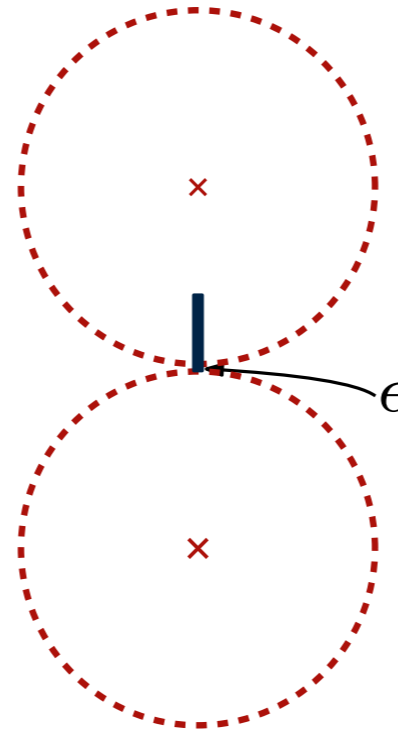


$$\tau_y \approx 2j\epsilon + x_j\epsilon^{1.5}$$

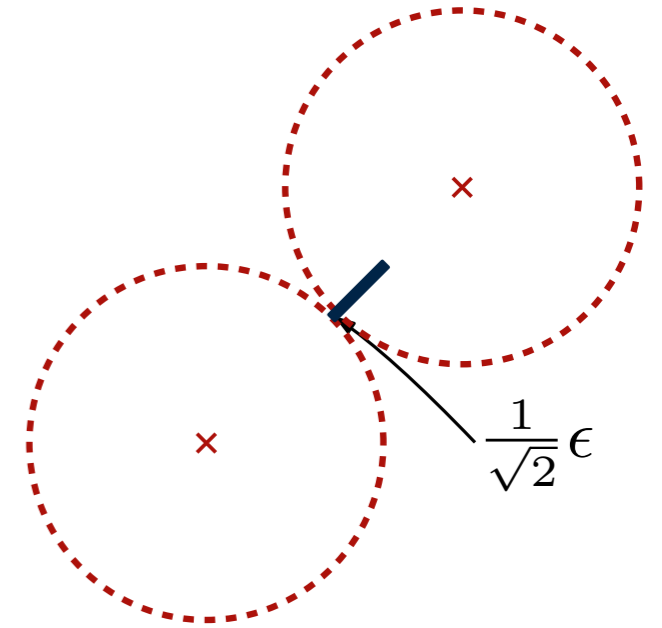
$$\text{Conv3SUM} \leq \delta_H^T \text{ in } L_2$$



$$\tau_x \approx 2i\epsilon + x_i\epsilon^{1.5}$$

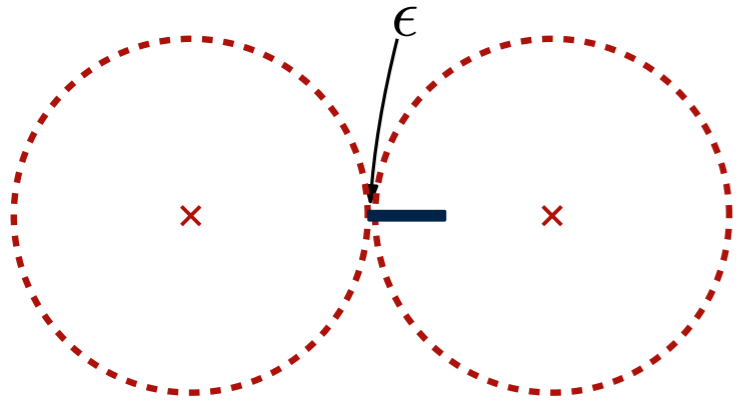


$$\tau_y \approx 2j\epsilon + x_j\epsilon^{1.5}$$

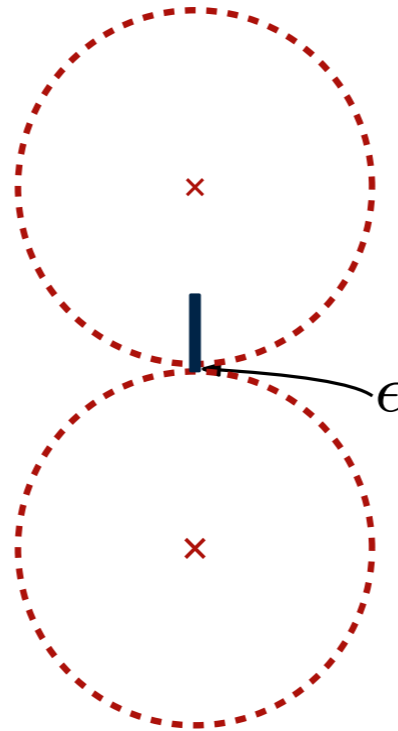


$$\tau_x + \tau_y \approx 2k\epsilon + x_k\epsilon^{1.5}$$

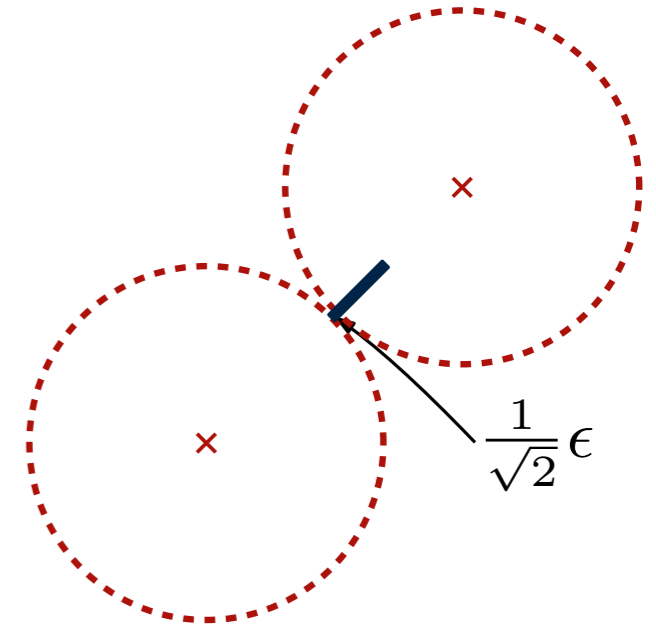
$$\text{Conv3SUM} \leq \delta_H^T \text{ in } L_2$$



$$\tau_x \approx 2i\epsilon + x_i\epsilon^{1.5}$$



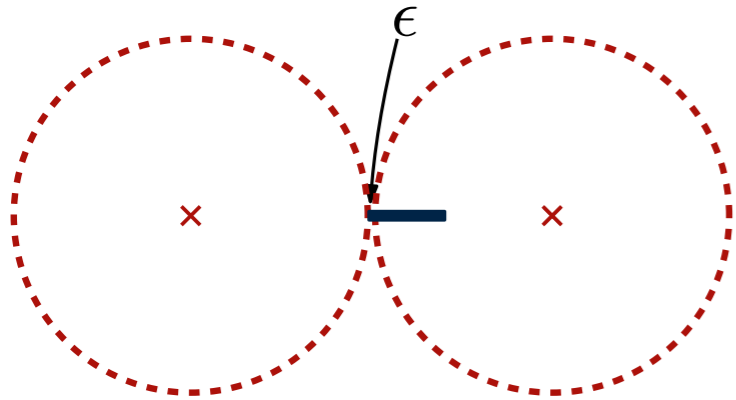
$$\tau_y \approx 2j\epsilon + x_j\epsilon^{1.5}$$



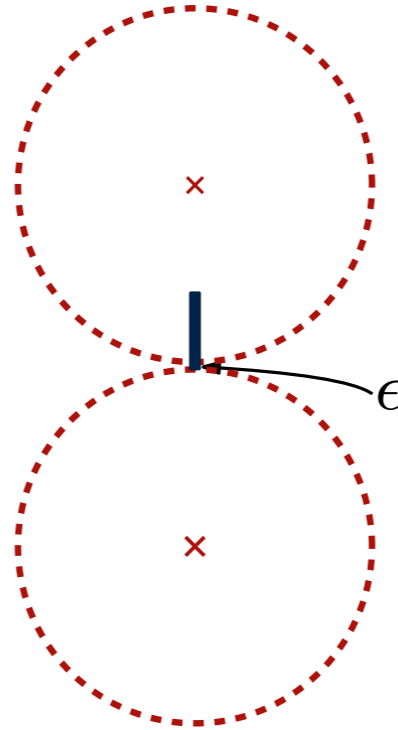
$$\tau_x + \tau_y \approx 2k\epsilon + x_k\epsilon^{1.5}$$

$$\exists i, j, k \in [n] : 2i\epsilon + 2j\epsilon - 2k\epsilon + x_i\epsilon^{1.5} + x_j\epsilon^{1.5} - x_k\epsilon^{1.5} \approx 0$$

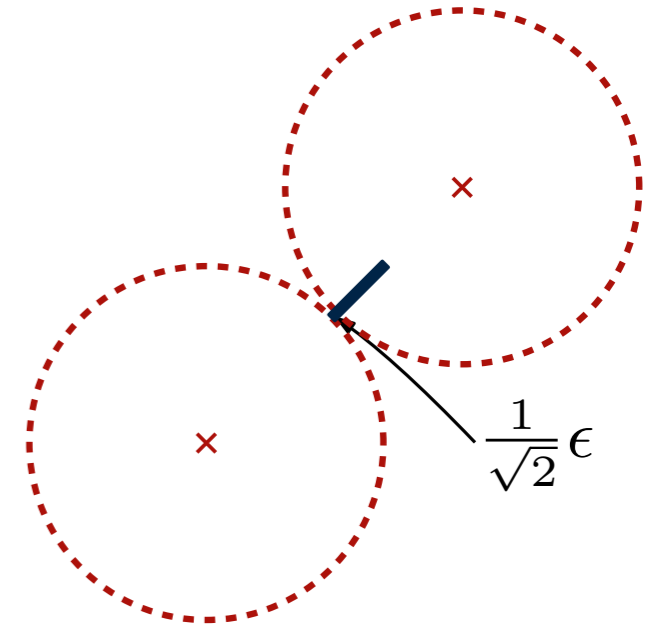
$$\text{Conv3SUM} \leq \delta_H^T \text{ in } L_2$$



$$\tau_x \approx 2i\epsilon + x_i\epsilon^{1.5}$$



$$\tau_y \approx 2j\epsilon + x_j\epsilon^{1.5}$$



$$\tau_x + \tau_y \approx 2k\epsilon + x_k\epsilon^{1.5}$$

$$\begin{aligned} & \exists i, j, k \in [n] : 2i\epsilon + 2j\epsilon - 2k\epsilon + x_i\epsilon^{1.5} + x_j\epsilon^{1.5} - x_k\epsilon^{1.5} \approx 0 \\ \iff & \exists i, j, k \in [n] : i + j = k \text{ and } x_i + x_j = x_k \end{aligned}$$

Summary



Summary

- Classic algorithms are conditionally optimal
 - L_2 for a special case



Summary

- Classic algorithms are conditionally optimal
 - L_2 for a special case
- Hardness from two different conjectures
 - SETH vs. 3SUM



Summary

- Classic algorithms are conditionally optimal
 - L_2 for a special case
 - Hardness from two different conjectures
 - SETH vs. 3SUM
-
- *Note:* Using $m \in \mathcal{O}(n)$ in the L_2 result encodes 4SUM
 - 4SUM is quadratic; want reduction from 5SUM

Summary

- Classic algorithms are conditionally optimal
 - L_2 for a special case
 - Hardness from two different conjectures
 - SETH vs. 3SUM
-
- *Note:* Using $m \in \mathcal{O}(n)$ in the L_2 result encodes 4SUM
 - 4SUM is quadratic; want reduction from 5SUM
 - *Open Question:* Is the balanced version in L_2 subcubic?

Summary

- Classic algorithms are conditionally optimal
 - L_2 for a special case
 - Hardness from two different conjectures
 - SETH vs. 3SUM
-
- *Note:* Using $m \in \mathcal{O}(n)$ in the L_2 result encodes 4SUM
 - 4SUM is quadratic; want reduction from 5SUM
 - *Open Question:* Is the balanced version in L_2 subcubic?



Vielen Dank!